

Higher Homotopy groups, cobordisms and Thom spaces

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Abstract: We study the higher homotopy groups of the Thom space of a vector bundle and connect them with the cobordism groups via the Thom isomorphism. We rely heavily on [1, Sec. 4.1] for Section 1, on [2, Sec. 1] and [3, Sec. 17] for Section 2 and on [3, Sec. 18] for Section 3.

1 Higher homotopy groups

In this section let X be any topological space and $I := [0, 1]$ be the unit interval. We call *topological pair* a pair (X, A) where $A \subset X$ is a subset and *topological triple* a triple (X, A, a) where $A \subset X$ is a subset and $a \in A$ is a point in A .

1.1 Homotopy groups

Definition 1.1 Let $x_0 \in X$ be a point and $n \in \mathbb{N}$.¹ Define

$$\pi_n(X, x_0) := \{f : I^n \longrightarrow X \text{ continuous} \mid f(\partial I^n) = \{x_0\}\} / \simeq_{\partial I^n},$$

where $\partial I^n = \{x \in I^n \mid x_i \in \{0, 1\} \text{ for at least one } i\}$ and two continuous maps $f_i : I^n \longrightarrow X$ with $f_i(\partial I^n) = \{x_0\}$ ($i = 0, 1$) satisfy $f_0 \simeq_{\partial I^n} f_1$ if and only if they are homotopic through maps satisfying the same property, i.e., iff there exists $H : [0, 1] \times I^n \longrightarrow X$ continuous with $H(i, \cdot) = f_i$ for both $i = 0, 1$ and $H(t, \partial I^n) = \{x_0\}$ for all $t \in [0, 1]$.

¹Call this \mathbb{N}_0 if you prefer.

A map $f : I^n \longrightarrow X$ with $f(\partial I^n) = x_0$ will be denoted by $f : (I^n, \partial I^n) \longrightarrow (X, x_0)$.² In case $n \geq 1$, the set $\pi_n(X, x_0)$ can be identified with that of pointed homotopy classes of continuous maps from the n -dimensional sphere $S^n = I^n/\partial I^n$ to X .

Examples 1.2

1. For $n = 0$ the set $\pi_0(X, x_0)$ can be identified with that of path-connected components of X . This is independent of x_0 because of $\partial I^0 = \emptyset$, in particular it can be denoted by $\pi_0(X)$ instead of $\pi_0(X, x_0)$.
2. For $n = 1$ the set $\pi_1(X, x_0)$ is the usual (pointed) fundamental group.

Proposition 1.3 *Let $x_0 \in X$ and $n \in \mathbb{N} \setminus \{0\}$. Then $\pi_n(X, x_0)$ has a natural group structure which is furthermore abelian if $n \geq 2$.*

From now on $\pi_n(X, x_0)$ will be called (in case $n \geq 1$) the n^{th} -homotopy group of X with basepoint x_0 . The group structure will be denoted multiplicatively if $n = 1$ and additively if $n \geq 2$.

We look at the dependence of the homotopy groups upon the basepoint. Given any two points $x_0, x_1 \in X$ joined by a continuous path $c : [0, 1] \longrightarrow X$ (where $c(i) = x_i$, $i = 0, 1$), there is a natural map $\left\{ f : (I^n, \partial I^n) \longrightarrow (X, x_0) \text{ continuous} \right\} \xrightarrow{\gamma_c} \left\{ f : (I^n, \partial I^n) \longrightarrow (X, x_1) \text{ continuous} \right\}$, where $\gamma_c(f) : (I^n, \partial I^n) \longrightarrow (X, x_1)$ is obtained as in the (missing) figure. Note that, if $n = 1$, the map $\gamma_c(f)$ is the composition of the paths usually denoted by $cf\bar{c}$ (see below), where $\bar{c}(t) := c(1 - t)$. The following lemma shows that γ_c induces a group isomorphism $\pi_n(X, x_0) \longrightarrow \pi_n(X, x_1)$ (where $n \geq 1$) which only depends on the homotopy class of c .

Lemma 1.4 (π_1 -action on π_n) *Let $x_0, x_1 \in X$ lie in the same path-connected component of X , let $c : [0, 1] \longrightarrow X$ be a continuous path from x_0 to x_1 and $f, f' : (I^n, \partial I^n) \longrightarrow (X, x_0)$ be continuous maps. Assume $n \geq 1$.*

- i) *If $f \simeq_{\partial I^n} f'$, then $\gamma_c(f) \simeq_{\partial I^n} \gamma_c(f')$. In particular, the map γ_c induces a map $\gamma_c : \pi_n(X, x_0) \longrightarrow \pi_n(X, x_1)$.*
- ii) *$\gamma_c(f \cdot f') \simeq_{\partial I^n} \gamma_c(f) \cdot \gamma_c(f')$. In particular, γ_c is a group homomorphism.*
- iii) *If $c' : [0, 1] \longrightarrow X$ is a continuous path from x_0 to x_1 with $c \simeq_{\partial I} c'$, then $\gamma_c(f) \simeq_{\partial I^n} \gamma_{c'}(f)$. In particular, γ_c only depends on the homotopy class of c (where homotopies fix ∂I).*

²More generally, the notation $f : (X, A) \longrightarrow (Y, B)$ means f is a map from X into Y sending $A \subset X$ into $B \subset Y$.

iii)' If c is constant, then $\gamma_c = \text{id}_{\pi_n(X, x_0)}$.

iv) If $c' : [0, 1] \rightarrow X$ is a continuous path from x_1 to $x_2 \in X$, then $\gamma_{cc'}(f) \simeq_{\partial I^n} \gamma_c(\gamma_{c'}(f))$, where $cc' : I \rightarrow X$, $t \mapsto c(2t)$ for $0 \leq t \leq \frac{1}{2}$ and $t \mapsto c'(2t - 1)$ for $\frac{1}{2} \leq t \leq 1$, is the natural composition of paths. In particular, γ_c is a group isomorphism.

As a consequence, $[c] \mapsto \gamma_c$ induces a group homomorphism $\pi_1(X, x_0) \rightarrow \text{Aut}(\pi_n(X, x_0))$, which turns $\pi_n(X, x_0)$ into a $\mathbb{Z}[\pi_1(X, x_0)]$ -module.

Note in particular that, if X is path connected (i.e., if $\pi_0(X) = 0$), the groups $\pi_n(X, x_0)$ and $\pi_n(X, x_1)$ are isomorphic for all $x_0, x_1 \in X$ and $n \geq 1$. In that case, they are usually denoted by $\pi_n(X)$ instead of $\pi_n(X, x_0)$.

Like the fundamental group, homotopy groups have the following functorial property.

Lemma 1.5 (π_n is a functor) *Let Y be any topological space with base-point y_0 and assume $n \geq 1$. Let $\varphi : (X, x_0) \rightarrow (Y, y_0)$ be any continuous map. Then $[f] \mapsto [\varphi \circ f]$ defines a group homomorphism $\pi_n(\varphi) : \pi_n(X, x_0) \rightarrow \pi_n(Y, y_0)$ satisfying:*

- i) *For any continuous map $\psi : (X, x_0) \rightarrow (Y, y_0)$ homotopic to φ (through maps sending x_0 to y_0), we have $\pi_n(\psi) = \pi_n(\varphi)$.*
- ii) *For any continuous map $\chi : (Y, y_0) \rightarrow (Z, z_0)$ (where Z is an arbitrary topological space and $z_0 \in Z$), we have $\pi_n(\chi \circ \varphi) = \pi_n(\chi) \circ \pi_n(\varphi)$. Moreover, $\pi_n(\text{id}_X) = \text{id}_{\pi_n(X, x_0)}$.*

As a straightforward consequence, the group homomorphism $\pi_n(\varphi)$ is an isomorphism as soon as φ is a homotopy equivalence (with basepoint).

The n^{th} homotopy group of a product is the product of the n^{th} homotopy groups of the factors:

Lemma 1.6 *Let $(X_i)_{i \in I}$ be an arbitrary family of path-connected topological spaces. Then $\pi_n(\prod_{i \in I} X_i) \rightarrow \prod_{i \in I} \pi_n(X_i)$, $[f] \mapsto ([f_i])_{i \in I}$ is a well-defined group isomorphism.*

Thanks to the lifting property of maps and homotopies through coverings, the higher homotopy groups do not see covering maps:

Lemma 1.7 *If $p : (X, x_0) \longrightarrow (Y, y_0)$ is a covering map, then $\pi_n(p)$ is an isomorphism for all $n \geq 2$.*

Examples 1.8

1. A space X is called *n-simple* if and only if it is path-connected and the π_1 -action on $\pi_k(X)$ (see Lemma 1.4) is trivial for all $1 \leq k \leq n$.
2. A space X is called *aspherical* if and only if it is path-connected and $\pi_n(X) = 0$ for all $n \geq 2$. For instance, all contractible spaces are aspherical. More generally, all spaces with contractible universal cover are aspherical.
3. In case $X = S^n$ one has $\pi_m(S^n) = 0$ for $m < n$ and $\pi_n(S^n) = \mathbb{Z}$ as a corollary of Hurewicz theorem below. However, the higher homotopy groups of S^n are only partially known, see table on [1, p.339].

Definition 1.9 *A topological space X is called n -connected if and only if $\pi_k(X) = 0$ for all $0 \leq k \leq n$.*

Obviously, a space X is n -connected with $n \geq 1$ if and only if every continuous map $S^n \rightarrow X$ is (freely) homotopic to a constant map.

1.2 Hurewicz theorem

Homology and homotopy are related via the famous Hurewicz theorem (the second part can be found in [2, p.207]):

Theorem 1.10 (Hurewicz) *Let X be an $(n-1)$ -connected topological space with $n \geq 2$. Then the (well-defined) group homomorphism*

$$\begin{aligned} h : \pi_k(X) &\longrightarrow H_k(X, \mathbb{Z}) \\ [f] &\longmapsto H_k(f)([S^k]) \end{aligned}$$

is an isomorphism for all $1 \leq k \leq n$, where $[S^k] \in H_k(S^k, \mathbb{Z}) \cong \mathbb{Z}$ is the generator fixed by the canonical orientation of S^k . If moreover X is a finite CW-complex, then h has finite kernel and cokernel for all $1 \leq k < 2n - 1$.

For $n = 1$ it is well-known that h is surjective with kernel the commutator subgroup $[\pi_1(X), \pi_1(X)]$ of $\pi_1(X)$, in particular h induces an isomorphism $\pi_1(X)/[\pi_1(X), \pi_1(X)] \longrightarrow H_1(X, \mathbb{Z})$.

There exists a relative version of this theorem: if a topological pair (X, A) is $(n - 1)$ -connected with $n \geq 2$ and 1-connected $A \neq \emptyset$ (meaning that $\pi_k(X, A) = 0$ for all $1 \leq k \leq n - 1$ and X is path-connected), then $\pi_k(X, A)$ is canonically isomorphic to $H_k(X, A)$ for all $1 \leq k \leq n$.

1.3 Relative homotopy groups

In this subsection, we denote by $J^{n-1} := \overline{\partial I^n \setminus I^{n-1}} \subset \partial I^n$, where $I^{n-1} = I^{n-1} \times \{0\} \subset \partial I^n$.

Definition 1.11 *Let $A \subset X$ be an arbitrary subset with $x_0 \in A$ and $n \in \mathbb{N} \setminus \{0\}$. Define*

$$\pi_n(X, A, x_0) := \{f : I^n \longrightarrow X \text{ cont.} \mid f(\partial I^n) \subset A \text{ and } f(J^{n-1}) = \{x_0\}\} / \simeq,$$

where two continuous maps $f_i : I^n \longrightarrow X$ with $f_i(\partial I^n) \subset A$ and $f_i(J^{n-1}) = \{x_0\}$ ($i = 0, 1$) satisfy $f_0 \simeq f_1$ if and only if they are homotopic through maps satisfying the same property, i.e., iff there exists $H : [0, 1] \times I^n \longrightarrow X$ continuous with $H(i, \cdot) = f_i$ for both $i = 0, 1$ and $H(t, \partial I^n) \subset A$ as well as $H(t, J^{n-1}) = \{x_0\}$ for all $t \in [0, 1]$.

As in the non-relative case, we have the following:

Proposition 1.12 *Let $A \subset X$ with $x_0 \in A$ and $n \in \mathbb{N} \setminus \{0, 1\}$. Then $\pi_n(X, A, x_0)$ has a natural group structure which is furthermore abelian if $n \geq 3$.*

In case $n \geq 2$, the set $\pi_n(X, A, x_0)$ is called n^{th} homotopy group of X relative to A . Note that, obviously, $\pi_n(X, \{x_0\}, x_0) = \pi_n(X, x_0)$. Beware there is no natural group structure in case $n = 1$.

The set $\pi_n(X, A, x_0)$ for $n \geq 2$ can be seen as that of all pointed homotopy classes of continuous maps $(D^n, S^{n-1} = \partial D^n, s_0) \rightarrow (X, A, x_0)$, where $D^n := \{x \in \mathbb{R}^n \mid |x| \leq 1\}$ is the usual closed n -dimensional disk and $s_0 \in S^{n-1}$ is e.g. the North pole.

As before, relative homotopy groups with different basepoints can be related in a natural way provided there is a curve joining them running in the subset A :

Lemma 1.13 (π_1 -action on π_n , relative case) *For $x_0, x_1 \in A \subset X$ assume the existence of a continuous map $c : I \longrightarrow A$ with $c(i) = x_i$, $i = 0, 1$. Then for every $n \geq 2$ there is a natural group isomorphism $\gamma_c : \pi_n(X, A, x_0) \rightarrow \pi_n(X, A, x_1)$, only depending on the homotopy class of c in A and satisfying $\gamma_{x_0} = \text{id}$ for the constant path x_0 as well as $\gamma_{cc'} = \gamma_c \circ \gamma_{c'}$ for $c' : [0, 1] \longrightarrow X$ continuous with $c'(0) = x_1$. In particular, there is a natural group homomorphism $\pi_1(A, x_0) \longrightarrow \text{Aut}(\pi_n(X, A, x_0))$.*

Again, if A is path-connected, the group $\pi_n(X, A, x_0)$ is often denoted simply by $\pi_n(X, A)$. Relative homotopy groups also give rise to a functor:

Lemma 1.14 (π_n is a functor, relative case) *Let (Y, B) be any topological pair, $y_0 \in B$ a point and assume $n \geq 2$. Let $\varphi : (X, A, x_0) \rightarrow (Y, B, y_0)$ be any continuous map (hence $\varphi(A) \subset B$ and $\varphi(x_0) = y_0$). Then $[f] \mapsto [\varphi \circ f]$ defines a group homomorphism $\pi_n(\varphi) : \pi_n(X, A, x_0) \rightarrow \pi_n(Y, B, y_0)$ satisfying:*

- i) *For any continuous map $\psi : (X, A, x_0) \rightarrow (Y, B, y_0)$ homotopic to φ (through maps $(X, A, x_0) \rightarrow (Y, B, y_0)$), we have $\pi_n(\psi) = \pi_n(\varphi)$.*
- ii) *For any continuous map $\chi : (Y, B, y_0) \rightarrow (Z, C, z_0)$ (where (Z, C, z_0) is an arbitrary topological triple), we have $\pi_n(\chi \circ \varphi) = \pi_n(\chi) \circ \pi_n(\varphi)$. Moreover, $\pi_n(\text{id}_X) = \text{id}_{\pi_n(X, A, x_0)}$.*

There is however a particular feature about relative homotopy groups:

Proposition 1.15 (long exact homotopy sequence) *Let (X, A, x_0) be a topological triple. Then the following sequence is exact:*

$$\dots \rightarrow \pi_n(A, x_0) \xrightarrow{\pi_n(i)} \pi_n(X, x_0) \xrightarrow{\pi_n(j)} \pi_n(X, A, x_0) \xrightarrow{\partial_n} \pi_{n-1}(A, x_0) \rightarrow \dots \rightarrow \pi_0(X, x_0),$$

where $i : (A, x_0) \rightarrow (X, x_0)$ and $j : (X, \{x_0\}, x_0) \rightarrow (X, A, x_0)$ are the natural inclusions and $\partial_n([f]) := [f|_{I^{n-1}}]$ (again $I^{n-1} \cong I^{n-1} \times \{0\} \subset \partial I^n$).

Exactness when no group structure is at hand means what it usually means: the set of elements mapped to 0 (which is the homotopy class of the constant map) is the image of the preceding arrow.

The proof of Proposition 1.15 is elementary and relies on the following so-called “compression lemma”:

Lemma 1.16 *Let $f(I^n, \partial I^n, J^{n-1}) \rightarrow (X, A, x_0)$ be a continuous map. Then $[f] = 0 \in \pi_n(X, A, x_0)$ if and only if f is homotopic relatively to $\partial I^n = S^{n-1}$ to a continuous map $f' : I^n \rightarrow A$.*

2 Cobordisms and cobordism groups

Unless otherwise mentioned, all manifolds in this section will be assumed to be smooth - but not necessarily connected!

³meaning that the homotopy restricted to ∂I^n does not depend on t

2.1 Cobordisms

Definition 2.1

- i) A (smooth) manifold triad is a triple $(W; V_0, V_1)$, where W is a compact manifold with boundary $\partial W = V_0 \amalg V_1$ (hence V_0 and V_1 are closed hypersurfaces of W).
- ii) A cobordism from a manifold M_0 to another manifold M_1 is a 5-tuple $(W; V_0, V_1; h_0, h_1)$, where $(W; V_0, V_1)$ is a manifold triad and $h_i : V_i \rightarrow M_i$ are (smooth) diffeomorphisms, $i = 0, 1$.

In particular, M_0 and M_1 have to be closed and to have the same dimension in order for a cobordism from M_0 to M_1 to exist.

Examples 2.2

1. Given any closed manifold M , there is always a cobordism from M to itself: just take $(W := [0, 1] \times M, V_0 := \{0\} \times M, V_1 := \{1\} \times M; h_0 := p_2, h_1 := p_2)$, where p_2 is the projection onto the second factor.
2. More generally, if $h : M \rightarrow M'$ is a diffeomorphism between two closed manifolds M and M' , then $(W := [0, 1] \times M, V_0 := \{0\} \times M, V_1 := \{1\} \times M; h_0 := p_2, h_1 := h \circ p_2)$ is a cobordism from M to M' .
3. If we accept \emptyset as a closed manifold (of any dimension), then for any compact manifold W , there is a cobordism from the closed manifold $M := \partial W$ to \emptyset . In particular, if $(W; V_0, V_1; h_0, h_1)$ is a cobordism from M_0 to M_1 , then W can also be seen as a cobordism from $M_0 \amalg M_1$ to \emptyset . For instance, using Example 2.2.1 just above, there always exists a cobordism from $M \amalg M$ to \emptyset .

Note that, if we did not impose W to be compact, then there would exist a cobordism from *every* boundaryless manifold M to \emptyset : just consider $W = M \times [0, \infty[$.

Definition 2.3 Two cobordisms $(W; V_0, V_1; h_0, h_1)$ and $(W'; V'_0, V'_1; h'_0, h'_1)$ from a manifold M_0 to a manifold M_1 are called equivalent if and only if there exists a diffeomorphism $g : W \rightarrow W'$ with $h'_i \circ g = h_i$ for both $i = 0, 1$ (in particular $g(V_i) = V'_i$).

This obviously defines an equivalence relation on all cobordisms from M_0 to M_1 . Cobordisms having a boundary piece in common can be glued together thanks to the following

Lemma 2.4 (Gluing cobordisms) *Let $(W; V_0, V_1)$ and $(W'; V'_1, V_2)$ be two manifolds triads with $V_1 \neq \emptyset$. Assume the existence of a diffeomorphism $V_1 \xrightarrow{h} V'_1$ and consider $W \cup_h W' := W \amalg W'/x \sim h(x)$ with its quotient topology. Then $W \cup_h W'$ admits a smooth manifold structure such that both inclusions $W, W' \hookrightarrow W \cup_h W'$ are smooth embeddings. This smooth structure is unique up to diffeomorphisms leaving $V_0, V_1 \cong V'_1$ and V_2 fixed.*

In a formal way, we can now form a category whose objects are the closed manifolds and whose morphisms from M_0 to M_1 are the equivalence classes of cobordisms from M_0 to M_1 . In case the corresponding morphism-sets are non-empty, the composition map $\text{Mor}(M_1, M_2) \times \text{Mor}(M_0, M_1) \rightarrow \text{Mor}(M_0, M_2)$ is given by the gluing procedure above (Lemma 2.4), where one should pay attention to the fact that the gluing is still well-defined on the level of cobordism-classes and that the composition we obtain is associative. Each monoid $\text{Mor}(M, M)$ has a neutral element, namely $\iota_M := [([0, 1] \times M, \{0\} \times M, \{1\} \times M; p_2, p_2)]$ (from Examples 2.2.1).

Note 2.5 Two cobordism-classes \mathcal{C} and \mathcal{C}' satisfying $\mathcal{C}\mathcal{C}' = \iota_M$ do not necessarily satisfy $\mathcal{C}'\mathcal{C} = \iota_M$, as the following simple example with $M = S^1$ shows [figure: 2 cylinders glued together; moreover, a disk of the left part belongs to the right one].

The set $\text{Mor}(M, M)$ of cobordism classes from M to itself will be henceforth denoted by H_M and that of *invertible* cobordism classes by G_M . Example 2.2.2 provides a map $\text{Diffeo}(M) \rightarrow H_M$ via $h \mapsto \mathcal{C}_h := [([0, 1] \times M, \{0\} \times M, \{1\} \times M; p_2, h \circ p_2)]$. It is elementary to show that $\mathcal{C}_h\mathcal{C}_{h'} = \mathcal{C}_{h' \circ h}$, thus $h \mapsto \mathcal{C}_h$ is a group-antihomomorphism $\text{Diffeo}(M) \rightarrow G_M$. It is however not injective in general. In order to describe its kernel, we need the notion of pseudo-isotopy.

Definition 2.6 *Two diffeomorphisms $h_0, h_1 : M \rightarrow M'$ are called pseudo-isotopic if and only if there exists a diffeomorphism $[0, 1] \times M \xrightarrow{g} [0, 1] \times M'$ such that $g(i, \cdot) = (i, h_i(\cdot))$ for both $i = 0, 1$.*

Recall that two diffeomorphisms $h_0, h_1 : M \rightarrow M'$ are called *isotopic* if and only if they are (smoothly) homotopic through diffeomorphisms, i.e., iff there exists a smooth map $H : [0, 1] \times M \rightarrow M'$ with $H(i, \cdot) = h_i$ for both $i = 0, 1$ and $H(t, \cdot) : M \rightarrow M'$ is a diffeomorphism for all $t \in [0, 1]$. Any isotopy is obviously a pseudo-isotopy (just set $g(t, x) := (t, H(t, x))$ for all $(t, x) \in [0, 1] \times M$), the converse being wrong in general.

Lemma 2.7 *Given any two closed manifolds M and M' , isotopy and pseudo-isotopy define equivalence relations on $\text{Diffeo}(M, M')$.*

We can now describe the kernel of the above map $h \mapsto \mathcal{C}_h$.

Proposition 2.8 *With the above notations, two diffeomorphisms $h_0, h_1 : M \rightarrow M'$ satisfy $\mathcal{C}_h = \mathcal{C}_{h'}$ if and only if they are pseudo-isotopic.*

2.2 Oriented cobordisms

There is an oriented version of cobordisms. Given an oriented manifold M , we shall denote by $-M$ the manifold with the same smooth structure and *opposite* orientation.

Definition 2.9

- i) An oriented manifold triad is manifold triad $(W; V_0, V_1)$, where W is oriented.*
- ii) An oriented cobordism from an oriented manifold M_0 to an oriented manifold M_1 is a 5-tuple $(W; V_0, V_1; h_0, h_1)$, where $(W; V_0, V_1)$ is an oriented manifold triad and $h_0 : V_0 \rightarrow M_0$, $h_1 : V_1 \rightarrow -M_1$ are (smooth) orientation-preserving diffeomorphisms.*

Beware that, if W is oriented, then ∂W carries an induced orientation as follows: a basis (X_2, \dots, X_{n+1}) of $T_x \partial W$ is oriented iff $(X_1, X_2, \dots, X_{n+1})$ is an oriented basis of $T_x W$ for an (hence all) *outward-pointing* vector $X_1 \in T_x W$ (and all $x \in \partial W$). In case W is 1-dimensional (hence a union of finitely many compact intervals), we define the orientation at a point $x \in \partial W$ to be 1 or -1 according to that point standing to the right or left end of the corresponding interval respectively.

2.3 Cobordism groups

Definition 2.10 *Two (closed) manifolds M_0 and M_1 are called*

- i) cobordant if and only if there exists a cobordism from M_0 to M_1 .*
- ii) oriented cobordant if and only if they are oriented and there exists an oriented cobordism from M_0 to M_1 .*

Both define equivalence relations on the set of all n -dimensional closed manifolds (resp. all oriented n -dimensional closed manifolds): each such manifold is bordant to itself (via ι_M , which also respects orientations in case M is oriented), symmetry is clear (change the orientation of W in the oriented case) and transitivity follows from Lemma 2.4, which also adapts to the oriented case and to the case where $M_1 = \emptyset$ (then just consider $W_0 \amalg W_2$, where $\partial W_0 = V_0$ and $\partial W_2 = V_2$).

Definition 2.11 *Let $n \in \mathbb{N}$.*

i) The n^{th} cobordism group is defined as

$$\Omega_n^{\text{O}} := \{\text{closed } n\text{-dimensional manifolds}\} / \sim,$$

where $M_0 \sim M_1$ iff there exists a cobordism from M_0 to M_1 .

ii) The n^{th} oriented cobordism group is defined as

$$\Omega_n^{\text{SO}} := \{\text{oriented closed } n\text{-dimensional manifolds}\} / \sim_{\text{or}},$$

where $M_0 \sim_{\text{or}} M_1$ iff there exists an oriented cobordism from M_0 to M_1 .

Both Ω_n^{O} and Ω_n^{SO} are abelian groups in a very natural way: define the additive law via $[M] + [M'] := [M \amalg M']$ in both cases. This is obviously well-defined, commutative and associative, with neutral element $[\emptyset]$, and the inverse of $[M]$ is $[M]$ in the unoriented case and $[-M]$ in the oriented one. Note in particular that $[M] = 0$ if and only if M bounds a compact manifold (and an oriented one in the oriented case). If one lets n runs over \mathbb{N} , then one actually obtains a (graded) ring structure on $\Omega^{\text{O}} := \bigoplus_{n \in \mathbb{N}} \Omega_n^{\text{O}}$ and $\Omega^{\text{SO}} := \bigoplus_{n \in \mathbb{N}} \Omega_n^{\text{SO}}$ via $[M] \cdot [N] := [M \times N]$.

Examples 2.12

1. For $n = 0$ it is easy to see that $\Omega_0^{\text{O}} \cong \mathbb{Z}_2$ since any two points can be joined by a segment. Moreover, $\Omega_0^{\text{SO}} \cong \mathbb{Z}$, where the isomorphism is given by the sum of the signs of the (finitely many) points.
2. For $n = 1$ both $\Omega_1^{\text{O}} = \Omega_1^{\text{SO}} = 0$ since S^1 obviously bounds an oriented manifold.
3. For $n = 2$ the oriented cobordism group Ω_2^{SO} also vanishes since any orientable closed surface bounds a compact manifold (called “handlebody” in higher genus). It is a bit of work to show that $\Omega_2^{\text{O}} \cong \mathbb{Z}_2$, with the class of the real projective plane as a generator.
4. It is however not trivial to show that $\Omega_3^{\text{SO}} = 0$ (Rokhlin’s theorem).

All cobordism groups turn out to be finitely generated, see Corollary 3.10.

3 Thom spaces, their homology and homotopy

3.1 The Thom space of a vector bundle

Definition 3.1 *Let $E \rightarrow B$ be a Riemannian (real) vector bundle over a topological space B . The Thom space of E is the topological quotient $T(E) := E/A$, where $A := \{X \in E, |X| \geq 1\}$.*

Notes 3.2

1. In particular there exists a preferred point $t_0 := [A] \in T(E)$.
2. The map $X \mapsto \frac{X}{\sqrt{1-|X|^2}}$ defines a homeomorphism $E \setminus A \rightarrow E$. In particular, if the base B is compact, then the Thom space of E is homeomorphic to the Alexandrov 1-point compactification $\hat{E} := E \sqcup \{\infty\}$ of E (map t_0 to ∞).
3. As another consequence of Note 3.2.2, Thom spaces associated to different Riemannian metrics on E are homeomorphic. Therefore, we do not need any longer to specify any metric on E .

If B is a CW-complex, so is its Thom space:

Proposition 3.3 *Let $E \rightarrow B$ be an n -ranked real vector bundle over a CW-complex B . Then $T(E)$ is an $(n-1)$ -connected CW-complex with exactly one 0-cell and one $(n+k)$ -cell for each k -cell in B .*

Proof: If $e_\alpha \subset B$ is an open k -dimensional cell (that is, e_α is homeomorphic to $\overset{\circ}{D}^k$), then $\pi^{-1}(e_\alpha) \cap (E \setminus A)$ is homeomorphic to $\overset{\circ}{D}^n \times \overset{\circ}{D}^k \cong \overset{\circ}{D}^{n+k}$, so that $\pi^{-1}(e_\alpha) \cap (E \setminus A)$ is an open $(n+k)$ -cell. Together with the 0-cell $\{t_0\}$, their disjoint union is $T(E)$. The characteristic maps gluing the cells together can be constructed as follows: if $\phi_\alpha : D^k \rightarrow B$ is a characteristic map for e_α (that is, ϕ_α is continuous, maps $\overset{\circ}{D}^k$ homeomorphically onto e_α and $\phi_\alpha(\partial D^k)$ is contained in the union of finitely many cells of lower dimension), then the pull-back bundle $\phi_\alpha^* E \rightarrow D^k$ is trivial because of D^k being contractible (see e.g. [4, Sec. 11.3] for the lifting property of homotopies in C^0 bundles), hence there exists a disk-bundle isomorphism $F_\alpha : D^k \times D^n \rightarrow \phi_\alpha^*(E \setminus A)$. Composing with the canonical projection $\overline{E \setminus A} \rightarrow T(E)$, we obtain a continuous map $\Phi_\alpha : D^k \times D^n \rightarrow T(E)$ which turns out to be a characteristic map for the open cell $\pi^{-1}(e_\alpha) \cap (E \setminus A)$. \square

3.2 Homology groups of the Thom spaces

Proposition 3.4 *Let $E \rightarrow B$ be an oriented n -ranked real vector bundle over a topological space B . Then there exists a canonical group isomorphism $H_{n+k}(T(E), t_0; \mathbb{Z}) \rightarrow H_k(B; \mathbb{Z})$ for all $k \in \mathbb{Z}$.*

Proof. Set $T_0 := T(E) \setminus \{0\text{-section}\}$. Since S^{n-1} is a deformation retract of $D^n \setminus \{0\}$, there exists a deformation retract from T_0 onto $\{t_0\}$. In particular $H_l(T_0, \{t_0\}; \mathbb{Z}) = 0$ for all $l \in \mathbb{Z}$. Thus, the long exact homology sequence for the triple $(T, T_0, \{t_0\})$ yields $H_l(T(E), \{t_0\}; \mathbb{Z}) \cong H_l(T(E), T_0; \mathbb{Z})$ for all $l \in \mathbb{Z}$. Since $\{t_0\}$ is closed and contained in the interior T_0 , an excision argument provides $H_l(T(E), T_0; \mathbb{Z}) \cong H_l(T(E) \setminus \{t_0\}, T_0 \setminus \{t_0\}; \mathbb{Z})$, which is by construction of $T(E)$ just $H_l(E, E_0; \mathbb{Z})$, where $E_0 := E \setminus \{0\text{-section}\}$. Now we know that there exists a unique cohomology class $u \in H^n(E, E_0; \mathbb{Z})$ such that $u|_F \in H^n(F, F_0)$ is the given orientation class of the fibre F , for every F ; moreover, the map $y \mapsto u \cap y$ is an isomorphism $H_{n+k}(E, E_0; \mathbb{Z}) \rightarrow H_k(E)$ (it is the so-called Thom isomorphism), for every $k \in \mathbb{Z}$. Since B , seen as the zero-section of E , is a deformation retract of E , we obtain by composing the isomorphisms above

$$H_{n+k}(T(E), t_0; \mathbb{Z}) \cong H_{n+k}(T(E), T_0; \mathbb{Z}) \cong H_{n+k}(E, E_0; \mathbb{Z}) \cong H_k(E; \mathbb{Z}) \cong H_k(B; \mathbb{Z}),$$

which was to be shown. \square

3.3 Homotopy groups of the Thom spaces

Corollary 3.5 *Let $E \rightarrow B$ be an oriented $n(\geq 2)$ -ranked real vector bundle over a finite CW-complex B . Then for any $m \in \{0, \dots, n-2\}$ there exists a canonical group homomorphism $\pi_{m+n}(T(E)) \rightarrow H_m(B; \mathbb{Z})$ which has finite kernel and co-kernel.*

Proof. Since by Proposition 3.3 the Thom space $T(E)$ is $(n-1)$ -connected and, by assumption, $m+n < 2n-1$, the Hurewicz homomorphism $h : \pi_{m+n}(T(E)) \rightarrow H_{m+n}(T(E); \mathbb{Z})$ has finite kernel and cokernel. Proposition 3.4 yields a canonical group isomorphism $H_{m+n}(T(E); \mathbb{Z}) \rightarrow H_m(B; \mathbb{Z})$, which concludes the proof. \square

From now on we concentrate on *smooth* vector bundles (over smooth bases). We denote by $s_0 : B \rightarrow E$ the zero-section of a vector bundle $E \rightarrow B$.

Theorem 3.6 *Let $E \rightarrow B$ be a smooth $n(\geq 1)$ -ranked real vector bundle over a smooth manifold B and $m \geq 0$ be a non-negative integer. Then for*

any continuous map $S^{m+n} \xrightarrow{f} T(E)$, there exists a continuous map $S^{m+n} \xrightarrow{g} T(E)$ which is homotopic to f , smooth on $g^{-1}(T(E) \setminus \{t_0\})$ and transverse to $B \cong s_0(B)$. Moreover, for any such map g , the cobordism class $[g^{-1}(B)] \in \Omega_m^O$ only depends on the homotopy class of g . In particular, $[g] \mapsto [g^{-1}(B)]$ defines a group homomorphism $\pi_{m+n}(T(E)) \rightarrow \Omega_m^O$ which induces a group homomorphism $\pi_{m+n}(T(E)) \rightarrow \Omega_m^{SO}$ in case E is oriented.

Proof: The proof of Theorem 3.6 relies on the following lemma:

Lemma 3.7 *Let $m, n \in \mathbb{N}$ and $f : V \rightarrow \mathbb{R}^n$ be a smooth map from an open subset $V \subset \mathbb{R}^{m+n}$ into \mathbb{R}^n . Assume that $0 \in \mathbb{R}^n$ is a regular value of f throughout some closed subset X of V (that is, $d_x f : \mathbb{R}^{m+n} \rightarrow \mathbb{R}^n$ is surjective for all $x \in X$). Let $K \subset V$ be a compact subset. Then for every $\varepsilon > 0$, there exists a smooth map $g : V \rightarrow \mathbb{R}^n$ such that $g|_{V \setminus K'} = f$ for some compact subset $K' \subset V$, the map g has 0 as a regular value throughout $X \cup K$ and $\|g - f\|_\infty < \varepsilon$.*

Proof: There exist a compact neighbourhood K' of K in V and a smooth function $\chi : V \rightarrow [0, 1]$ which is 1 on a neighbourhood of K and vanishes outside K' . Given any regular value y of f , consider the map $g_y : V \rightarrow \mathbb{R}^n$, $x \mapsto f(x) - \chi(x) \cdot y$. Then g_y is smooth, has 0 as a regular value throughout $(X \setminus K') \cup K$ (because of $\chi|_K = 1$ and y being a regular value of f), coincides with f outside K' and satisfies $\|g_y - f\|_\infty \leq |y|$. By the Sard-Brown theorem the set of regular values of a smooth map is dense (in the target manifold), we can achieve $\|g_y - f\|_\infty < \varepsilon$ by choosing y sufficiently close to 0 in \mathbb{R}^n . Moreover, since actually $\|g_y - f\|_{C^1} < C(y)|y|$ for some continuous and bounded function C of y , we can by possibly making ε smaller ensure that 0 remains a regular value of g_y throughout $X \cap K'$ as well. On the whole, there is an appropriate choice of y making g_y fulfill all required conditions. \checkmark

First, we have to accept the existence of a map $f_0 : S^{m+n} \rightarrow T(E)$, homotopic to f with $f_0^{-1}(\{t_0\}) = f^{-1}(\{t_0\})$ and such that f_0 is smooth outside $f_0^{-1}(\{t_0\})$ (see [4, Sec. 6.7]). Now we prove the result for f_0 instead of f . Since $f_0^{-1}(B)$ is compact, included in $f_0^{-1}(T(E) \setminus \{t_0\})$ and E is locally trivial, there exist finite families $\{K_i\}_{1 \leq i \leq r}$ and $\{V_i\}_{1 \leq i \leq r}$ of compact subsets of $f_0^{-1}(T(E) \setminus \{t_0\})$ and finitely many trivializing open subsets $\{U_i\}_{1 \leq i \leq r}$ for E (i.e., $\pi^{-1}(U_i) \cong U_i \times \mathbb{R}^n$ where $E \xrightarrow{\pi} B$ is the projection map) with $f_0^{-1}(B) \subset \bigcup_{i=1}^r \overset{\circ}{K}_i \subset \bigcup_{i=1}^r K_i \subset \bigcup_{i=1}^r V_i$, and $f_0(V_i) \subset U_i$ for each $1 \leq i \leq r$. We construct inductively on i continuous maps $f_i : S^{m+n} \rightarrow T(E)$, $1 \leq i \leq r$, satisfying:

1. The map f_i is homotopic and as close as desired to f_{i-1} , $f_i^{-1}(\{t_0\}) = f_0^{-1}(\{t_0\})$, f_i is smooth outside $f_0^{-1}(\{t_0\})$, $f_i|_{S^{m+n} \setminus K'_i} = f_{i-1}|_{S^{m+n} \setminus K'_i}$ for some compact subset K'_i of V_i ;
2. The map f_i is a fibrewise deformation of f_{i-1} , that is, $\pi \circ f_i = \pi \circ f_0$ on $S^{m+n} \setminus f_0^{-1}(\{t_0\})$;
3. The map f_i is transverse to B throughout $K_1 \cup \dots \cup K_i$.

The construction of f_i from f_{i-1} is an elementary application of Lemma 3.7. First we only need to care for f_i on the open subset $S^{m+n} \setminus f_0^{-1}(\{t_0\})$. Let $\rho_i := p_2^{(i)} : \pi^{-1}(U_i) \rightarrow \mathbb{R}^n$ be the second projection coming from the trivialization over U_i . To construct f_i on V_i we only need to define $\rho_i \circ f_i$, since the first component of f_i is determined by $\pi \circ f_i = \pi \circ f_0$. By assumption, $\rho_i \circ f_{i-1}$ has 0 as a regular value throughout $V_i \cap (K_1 \cup \dots \cup K_{i-1})$ (the differential $d\rho_i$ is fibrewise a linear isomorphism). Considering V_i as an open subset of $\mathbb{R}^{m+n} \cong S^{m+n} \setminus \{\text{pt}\}$ (make V_i slightly smaller in case $V_i = S^{m+n}$) and $\rho_i \circ f_{i-1}$ as a smooth function $V \rightarrow \mathbb{R}^n$ with 0 as a regular value throughout the closed subset $X_i := V_i \cap (K_1 \cup \dots \cup K_{i-1})$ of V_i , Lemma 3.7 provides a smooth map $r_i : V_i \rightarrow \mathbb{R}^n$, coinciding with $\rho_i \circ f_{i-1}$ outside some compact subset K'_i of V_i and having 0 as a regular value throughout $X_i \cup K_i = V_i \cap (K_1 \cup \dots \cup K_i)$. Define f_i to be f_{i-1} on $S^{m+n} \setminus K'_i$ and $f_i := (\pi \circ f_0, r_i)$ on V_i . Then f_i is, by construction of r_i , well-defined as a map $S^{m+n} \rightarrow T(E)$, satisfies $f_i|_{S^{m+n} \setminus K'_i} = f_{i-1}|_{S^{m+n} \setminus K'_i}$, in particular $f_i^{-1}(\{t_0\}) = f_0^{-1}(\{t_0\})$, f_i is smooth outside $f_0^{-1}(\{t_0\})$ and transverse to B throughout $K_1 \cup \dots \cup K_i$, as well as $\pi \circ f_i = \pi \circ f_0$ outside $f_0^{-1}(\{t_0\})$. On the whole, the map f_i satisfies all we want. Now start with f_0 , take $K_0 := \emptyset$ (keep no other condition in mind that f_0 is smooth outside $f_0^{-1}(\{t_0\})$) and construct successively f_1, \dots, f_r as above. Set $g := f_r$, then g does the job... provided the inclusion $f_r^{-1}(B) \subset K_1 \cup \dots \cup K_r$ is fulfilled. Note that the homotopy property $f_{i-1} \simeq f_i$ at each step can be achieved by choosing r_i sufficiently close to $\rho_i \circ f_{i-1}$. Even better: since f_0 is away from B on the compact subset $S^{m+n} \setminus (\bigcup_{i=1}^r K_i)$, one can choose at each step the corresponding ε_i small enough such that f_i again remains away from B . Therefore, by an appropriate choice of the r_i 's at each step, we obtain the required map g . Next we prove that the oriented cobordism class of the submanifold $g^{-1}(B)$ only depends on the homotopy class of g . Let $g, g' : S^{m+n} \rightarrow T(E)$ be continuous maps with $g^{-1}(\{t_0\}) = g'^{-1}(\{t_0\})$, g and g' are smooth outside $g^{-1}(\{t_0\})$, are homotopic to each other and transverse to B . Then there exists a homotopy (actually homotopic to the homotopy from g to g') $h_0 : [0, 1] \times S^{m+n} \rightarrow T(E)$ from g to g' which is smooth outside $h_0^{-1}(\{t_0\})$ and

satisfies $h_0(t, \cdot) = g$ for all $0 \leq t \leq \frac{1}{3}$ as well as $h_0(t, \cdot) = g'$ for all $\frac{2}{3} \leq t \leq 1$. As above one constructs a new continuous map $h : [0, 1] \times S^{m+n} \rightarrow T(E)$ with $h^{-1}(\{t_0\}) = h_0^{-1}(\{t_0\})$, which is smooth outside that subset, coincides with h_0 outside a compact subset of $]0, 1[\times S^{m+n}$ and is transverse to B ; beware that the transversality throughout $([0, \frac{1}{3}] \cup [\frac{2}{3}, 1]) \times S^{m+n}$ has to be required to be preserved at each step. Now $h^{-1}(B)$ is a cobordism⁴ from $g^{-1}(B) = h^{-1}(B) \cap (\{0\} \times S^{m+n})$ to $g'^{-1}(B) = h^{-1}(B) \cap (\{1\} \times S^{m+n})$ and induces the desired orientations on both $g^{-1}(B)$ and $g'^{-1}(B)$. The groups laws on $\pi_{m+n}(T(E), t_0)$ and Ω_n^{SO} are respected by the assignment $[g] \mapsto [g^{-1}(B)]$, since by definition of the composition in $\pi_{m+n}(T(E))$ and because of $t_0 \notin B$ the submanifold we obtain from $f \vee f'$ is $g^{-1}(B) \amalg g'^{-1}(B)$.

By forgetting about orientations, the proof of the oriented case obviously adapts to the non-orientable case, giving rise to a group homomorphism $\pi_{m+n}(T(E)) \rightarrow \Omega_m^{\text{O}}$ for all smooth n -ranked real vector bundles $E \rightarrow B$ and all $m \in \mathbb{N}$. This concludes the proof of Theorem 3.6. \square

Next we look at the particular case where E is either the universal bundle $\gamma^n := \gamma^n(\mathbb{R}^\infty) \rightarrow G_n(\mathbb{R}^\infty)$ or the oriented universal bundle $\widetilde{\gamma}^n := \widetilde{\gamma}^n(\mathbb{R}^\infty) \rightarrow \widetilde{G}_n(\mathbb{R}^\infty)$. The main theorem of this section is the following:

Theorem 3.8 (R. Thom) *Let $n \in \mathbb{N} \setminus \{0, 1\}$. Then for all $m \in \{0, \dots, n-2\}$, the homomorphisms $\pi_{m+n}(T(\gamma^n)) \rightarrow \Omega_m^{\text{O}}$ and $\pi_{m+n}(T(\widetilde{\gamma}^n)) \rightarrow \Omega_m^{\text{SO}}$ of Theorem 3.6 are isomorphisms.*

Proof: As in [3], we only prove the surjectivity, which follows from the

Lemma 3.9 *Let $k, m, n \in \mathbb{N}$ with $m \leq k, n$. Then the homomorphisms $\pi_{m+n}(T(\gamma^n(\mathbb{R}^{n+k}))) \rightarrow \Omega_m^{\text{O}}$ and $\pi_{m+n}(T(\widetilde{\gamma}^n(\mathbb{R}^{n+k}))) \rightarrow \Omega_m^{\text{SO}}$ of Theorem 3.6 are isomorphisms.*

Proof: Pick $[M^m] \in \Omega_m^{\text{SO}}$. By the Whitney embedding theorem, there exists an embedding $M^m \hookrightarrow \mathbb{R}^{m+n}$ because of $n \geq m$. Since M^m is embedded in \mathbb{R}^{m+n} , there exists an open tubular neighbourhood U of M in \mathbb{R}^{m+n} which is diffeomorphic to the normal bundle $T^\perp M \rightarrow M$ of M in \mathbb{R}^{m+n} . Composing the Gauß map $M \rightarrow \widetilde{G}_n(\mathbb{R}^{m+n})$, $x \mapsto T_x^\perp M$ with the canonical embedding by the first coordinates $\widetilde{G}_n(\mathbb{R}^{m+n}) \rightarrow \widetilde{G}_n(\mathbb{R}^{k+n})$, we obtain a map $M \rightarrow \widetilde{G}_n(\mathbb{R}^{n+k})$

⁴If $f : W \rightarrow N$ is a smooth map from a manifold with boundary to another manifold and $y \in N$ is a regular value of f (meaning that $d_x f : T_x W \rightarrow T_y N$ and $d_x(f|_{\partial W}) : T_x \partial W \rightarrow T_y N$ are surjective for $x \in f^{-1}(\{y\}) \cap (W \setminus \partial W)$ and $x \in f^{-1}(\{y\}) \cap \partial W$ respectively), then $f^{-1}(\{y\})$ is a smooth submanifold with boundary $f^{-1}(\{y\}) \cap \partial W$. Similarly, if B is a boundaryless submanifold of N and f is transverse to B in a sense analogous to the one above, then $f^{-1}(B)$ is a manifold with boundary $f^{-1}(B) \cap \partial W$.

which obviously pulls $\widetilde{\gamma}^n(\mathbb{R}^{n+k}) \rightarrow \widetilde{G}_n(\mathbb{R}^{n+k})$ back to $T^\perp M$. Therefore, we obtain a smooth map $U \rightarrow \widetilde{\gamma}^n(\mathbb{R}^{n+k})$ which is fibrewise a diffeomorphism and hence transverse to the zero-section $B = \widetilde{G}_n(\mathbb{R}^{n+k})$ of $\widetilde{\gamma}^n(\mathbb{R}^{n+k}) \rightarrow \widetilde{G}_n(\mathbb{R}^{n+k})$. Composing this map with the inclusion $\widetilde{\gamma}^n(\mathbb{R}^{n+k}) \rightarrow T(\widetilde{\gamma}^n(\mathbb{R}^{n+k}))$, we obtain a continuous map $U \rightarrow T(\widetilde{\gamma}^n(\mathbb{R}^{n+k}))$ which can be extended to a continuous map $S^{m+n} = \mathbb{R}^{m+n} \sqcup \{\infty\} \xrightarrow{g} T(\widetilde{\gamma}^n(\mathbb{R}^{n+k}))$ by sending $\mathbb{R}^{m+n} \setminus U$ onto $\{t_0\}$. By construction, g is smooth outside $g^{-1}(\{t_0\})$, transverse to $B = \widetilde{G}_n(\mathbb{R}^{n+k})$ with $g^{-1}(B) = M$. Moreover, the orientation of M obviously coincides with that induced by g and $\widetilde{\gamma}^n(\mathbb{R}^{n+k}) \rightarrow \widetilde{G}_n(\mathbb{R}^{n+k})$. In other words, $[M]$ is the image of g through the homomorphism $\pi_{m+n}(T(\widetilde{\gamma}^n(\mathbb{R}^{n+k}))) \rightarrow \Omega_m^{\text{SO}}$. Note that, forgetting again about the orientation, the same arguments show that the homomorphism $\pi_{m+n}(T(\gamma^n(\mathbb{R}^{n+k}))) \rightarrow \Omega_m^{\text{O}}$ is surjective. \checkmark

For sufficiently large k the inclusion $\gamma^n(\mathbb{R}^{n+k}) \rightarrow \widetilde{\gamma}^n(\mathbb{R}^\infty)$ induces an isomorphism $\pi_{m+n}(T(\widetilde{\gamma}^n(\mathbb{R}^{n+k}))) \rightarrow \pi_{m+n}(T(\widetilde{\gamma}^n(\mathbb{R}^\infty)))$, therefore the group homomorphism $\pi_{m+n}(T(\widetilde{\gamma}^n(\mathbb{R}^\infty))) \rightarrow \Omega_m^{\text{SO}}$ is an isomorphism. The non-orientable case is analogous. \square

Corollary 3.10 *The oriented cobordism group Ω_m^{SO} is finite for all $m \notin 4\mathbb{Z}$ and finitely generated with rank the number of partitions of $\frac{m}{4}$ for $m \in 4\mathbb{Z}$.*

Proof. By Lemma 3.9, the group Ω_m^{SO} is the image of the homomorphism $\pi_{m+n}(T(\widetilde{\gamma}^n(\mathbb{R}^{n+k}))) \rightarrow \Omega_m^{\text{SO}}$ as soon as $k, n \geq m$. But since $\widetilde{G}_n(\mathbb{R}^{n+k})$ is a finite CW-complex, Corollary 3.5 states the existence of a group homomorphism $\pi_{m+n}(T(\widetilde{\gamma}^n(\mathbb{R}^{n+k}))) \rightarrow H_m(\widetilde{G}_n(\mathbb{R}^{n+k}); \mathbb{Z})$ with finite kernel and cokernel, at least if $n \geq m + 2$. Now $H_m(\widetilde{G}_n(\mathbb{R}^{n+k}); \mathbb{Z})$ is finite if $m \notin 4\mathbb{Z}$ and finitely generated with rank equal to the number p of partitions of $\frac{m}{4}$ if $m \in 4\mathbb{Z}$. Therefore Ω_m^{SO} is finite if $m \notin 4\mathbb{Z}$ and is finitely generated with rank at most the number of partitions of $\frac{m}{4}$ if $m \in 4\mathbb{Z}$. Now an explicit computation shows that the products $\mathbb{C}P^{2k_1} \times \dots \times \mathbb{C}P^{2k_r}$, where k_1, \dots, k_r run over the set of partitions of $r = \frac{m}{4}$, all have different Pontrjagin numbers (see [3, Sec. 16 & 17]), therefore they give linearly independent elements in Ω_m^{SO} . On the whole the rank of Ω_m^{SO} is at least and hence equal to p in the case where $m \in 4\mathbb{Z}$. \square

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